



NILASAILA INSTITUTE OF SCIENCE & TECHNOLOGY
SERGARH-756060, BALASORE (ODISHA)
(Approved by AICTE& affiliated to SCTE&VT, Odisha)



LESSON PLAN

SUBJECT: TH-4(CAD/CAM & AUTOMATION)

CHAPTERWISE DISTRIBUTION OF PERIODS

SLNO	NAME OF THE CHAPTER AS PER SYLLABUS	NO OF SYLLABUS AS PER SYLLABUS	NO OF PERIODS ACTUALLY NEEDED
1	INTRODUCTION TO CAD/CAM	6	6
2	GEOMETRICMODELING	12	12
3	INTRODUCTION TO COMPUTER NUMERICAL CONTROL	6	6
4	PARTPROGRAMMING	14	14
5	INDUSTRIAL ROBOTICS	12	12
6	AUTOMATION	10	10
	TOTAL PERIOD	60	60

Discipline: AUTOMOBILE ENGINEERING	Semester: 6th	Name of the Teaching Faculty: Er.BISHNU CHARAN JENA
Week	Class Day	Theory / Practical Topics
1 st	1 st	1. Introduction to CAD / CAM
	2 nd	Computers in industrial manufacturing.
	3 rd	Computers in industrial manufacturing.
	4 th	Product Cycle, CAD /CAM Hardware:Basic structure, CPU, Memory, I/O devices, Storage devices and system configuration.
	5 th	Product Cycle, CAD /CAM Hardware:Basic structure, CPU, Memory, I/O devices, Storage devices and system configuration.
2 nd	1 st	Product Cycle, CAD /CAM Hardware:Basic structure, CPU, Memory, I/O devices, Storage devices and system configuration.
	2 nd	CLASS TEST
	3 rd	2. Geometric Modelling :
	4 th	Requirement of geometric modeling.
	5 th	Requirement of geometric modeling.
3 rd	1 st	Types of Geometric models.
	2 nd	<i>Types of Geometric models.</i>
	3 rd	<i>Types of Geometric models.</i>
	4 th	<i>Types of Geometric models.</i>
	5 th	Geometri construction method-sweep, solid moedlling – Primitives & Boolean operations, free formed surfaces (Classification of surface only) (No numerical treatment).

4 th	1 st	Geometri construction method-sweep, solid moedlling – Primitives & Boolean operations, free formed surfaces (Classification of surface only) (No numerical treatment).
	2 nd	Geometri construction method-sweep, solid moedlling – Primitives & Boolean operations, free formed surfaces (Classification of surface only) (No numerical treatment).
	3 rd	Geometri construction method-sweep, solid moedlling – Primitives & Boolean operations, free formed surfaces (Classification of surface only) (No numerical treatment).
	4 th	CLASS TEST
	5 th	3. Introduction to computer numerical Control
5 th	1 st	Introduction – NC, CNC, DNC,
	2 nd	Introduction – NC, CNC, DNC,
	3 rd	<i>Advantages of CNC</i>
		Advantages of CNC
	4 th	The coordinate system in CNC
6 th	1 st	The coordinate system in CNC
	2 nd	Motion control system – point to point, straight line, Continuous path
	3 rd	Motion control system – point to point, straight line, Continuous path
	4 th	Motion control system – point to point, straight line, Continuous path
7 th	1 st	Application of CNC.
	2 nd	CLASS TEST
	3 rd	4. Part programming :
	4 th	Fundamentals,
	5 th	Fundamentals,

8 th	1 st	<i>Manual part programming</i>
	2 nd	Manual part programming
	3 rd	NC- Words, Programming format
	4 th	NC- Words, Programming format
9 th	1 st	NC- Words, Programming format
	2 nd	Part programming
	3 rd	Part programming
	4 th	use of subroutines and do loops,
10 th	1 st	use of subroutines and do loops,
	2 nd	computer aided part programming
	3 rd	<i>computer aided part programming</i>
	4 th	<i>computer aided part programming</i>
	5 th	CLASS TEST
11 th	1 st	5. Industrial Robotics
	2 nd	Introduction, physical configuration
	3 rd	Introduction, physical configuration
	4 th	basic robot motions, technical features such as work volume,precision and speed of movement,weight carrying capacity , drive system,End effectors,robot sensorsa
	5 th	basic robot motions, technical features such as work volume,precision and speed of movement,weight carrying capacity , drive system,End effectors,robot sensorsa

12 th	1 st	basic robot motions, technical features such as work volume,precision and speed of movement,weight carrying capacity , drive system,End effectors,robot sensorsa
	2 nd	basic robot motions, technical features such as work volume,precision and speed of movement,weight carrying capacity , drive system,End effectors,robot sensorsa
	3 rd	Application- Material transfer, machine loading,welding,spray coating,processing operation,assembly,inspection.
	4 th	Application- Material transfer, machine loading,welding,spray coating,processing operation,assembly,inspection.
13 th	1 st	Application- Material transfer, machine loading,welding,spray coating,processing operation,assembly,inspection.
	2 nd	Application- Material transfer, machine loading,welding,spray coating,processing operation,assembly,inspection.
	3 rd	CLASS TEST
	4 th	6. Automation :
14 th	1 st	Basic elements of automated system,
	2 nd	Basic elements of automated system,
	3 rd	advanced automation functions
	4 th	advanced automation functions
	5 th	advanced automation functions
15 th	1 st	levels of automation.
	2 nd	levels of automation.
	3 rd	Flexible manufacturing : Introduction FMS equipments, FMS application. Introduction to CIM.
	4 th	Flexible manufacturing : Introduction FMS equipments, FMS application. Introduction to CIM.
	5 th	CLASS TEST

